

Change detection approach for the monitoring of the recovery phase in the aftermath of a disaster. The example of Haiti RO

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• Introduction

- Addressed problem and Project overview
- Change detection methodologies
- The proposed approach

Outline

- Key ideas of Region-based and Markov random fields
- Proposed energy function
- Experimental results
 - Experiments on 10 m resolution data
 - Experiments on 2 m resolution data
- Conclusion



Introduction

Research activity framed within the project "Committee on Earth Observation Satellites – Disaster Risk Management "(CEOS-DRM)

- Contribution to the activity of CEOS Working Group on Disasters (Recovery Observatory and GEO-DARMA pilot);
- Development of change detection methodologies for the environmental monitoring of the recovery phase after disasters;
- Special focus on both radar and optical sensors (COSMO-SkyMed and Plèiades data);
- Case study: aftermath of Hurricane Matthew, which struck the southwest department of Haiti in October 2016 leading to more than 1000 lives lost and to severe damage to buildings, forests, and agriculture.



Multitemporal fusion at the feature level

- multitemporal information extracted through the generation of new features able to emphasize changes in the data set;
- mainly related to unsupervised detection approaches;
- mostly (almost always) single-sensor;
- final product usually limited to binary "change vs. no-change" case.

Multitemporal fusion at the decision level

- higher semantic level analysis;
- explicit characterization of the typology of occurred changes;
- mainly related to supervised (possibly semi-supervised) approaches;
- especially relevant for detailed post-analysis (e.g., monitoring, recovery analysis).



Data set: multitemporal, very high resolution (VHR), multisensor imagery

Objective:

Formalize the change-detection problem through a multitemporal supervised classification approach for multisensor optical/SAR data taking advantage from the temporal and spatial information associated with the images



Key approaches:

- Multiscale region-based concepts
- Markov random field (MRF) modeling



Region-based approach:

- characterization of the geometrical structure associated with VHR images;
- takes advantage of both fine-scale and coarse-scale spatial behaviors through multiple segmentation maps at different spatial scales.

MRFs:

- major families of (undirected) probabilistic graphical models;
- naturally formalize global Bayesian decision criteria;
- capability to fuse together data belonging to different sources;
- integration of spatial context and temporal correlation associated with images acquired at different dates on the same area;
- classification through minimum-energy rules.



The contextual spatial information related to each image, the temporal correlation between the images, and the multiscale information provided by the set of segmentation maps are fused together as a linear combination of different energy contributions:



Energy contribution related to each segmentation map Spatial-contextual energy contribution associated with the image on each date



- Represented by the Probability Mass Function (PMF) of the considered segment labels conditioned to the thematic classes
- Estimation is based on a relative frequency approach
- Requires as input classification maps obtained from the acquired image

$$U(Y_{0}, Y_{1}|S_{0}, S_{1}) = -\sum_{t=0}^{1} \left[\sum_{i \in I} \sum_{q=1}^{Q} \alpha_{qt} \ln P(s_{iqt}|y_{it}) - \beta_{t} \sum_{i \sim j} \delta(y_{it}, y_{jt}) + \gamma_{t} \sum_{i \bowtie j} P(y_{it}|y_{j,1-t}) \right]$$

Energy contribution related to each segmentation map Spatial-contextual energy contribution associated with the image on each date



Proposed MRF energy function



$$U(Y_{0}, Y_{1}|S_{0}, S_{1}) = -\sum_{t=0}^{1} \left[\sum_{i \in I} \sum_{q=1}^{Q} \alpha_{qt} \ln P(s_{iqt}|y_{it}) - \beta_{t} \sum_{i \sim j} \delta(y_{it}, y_{jt}) + \gamma_{t} \sum_{i \bowtie j} P(y_{it}|y_{j,1-t}) \right]$$

Energy contribution related to each segmentation map Spatial-contextual energy contribution associated with the image on each date



Proposed MRF energy function

Given the pixelwise posterior probability of the class labels, the estimation of the transition probabilities is performed through the expectation-maximization (EM) method



$$U(Y_{0}, Y_{1}|S_{0}, S_{1}) = -\sum_{t=0}^{1} \left[\sum_{i \in I} \sum_{q=1}^{Q} \alpha_{qt} \ln P(s_{iqt}|y_{it}) - \beta_{t} \sum_{i \sim j} \delta(y_{it}, y_{jt}) + \gamma_{t} \sum_{i \bowtie j} P(y_{it}|y_{j,1-t}) \right]$$

Energy contribution related to each segmentation map Spatial-contextual energy contribution associated with the image on each date



Parameter estimation:

The estimation of the weights (α , β , γ) of each energy contribution is performed through the method presented in (De Giorgi et al., 2015), which is based on a mean square error approach and on the sequential minimal optimization (SMO) algorithm.

Energy minimization by graph cut:

- energy minimization as a maximum flow problem
- global minimum for binary classification
- "strong" local minimum in the multiclass case





Proposed methodological approach





Examples of results

> Data set acquired during 2016 and 2017



Jérémie_2016:

 Pansharpened Pléiades multispectral acquisition date 7/10/2016 (few days after Hurricane Matthew), 4 channels, native resolution: 2m for multispectral channels and 0.5 m for the panchromatic channel)



Jérémie_2017":

- Pléiades multispectral, acquisition date 18/10/2017, 4 channels, resolution 2 m;
- COSMO-SkyMed Spotlight, acquisition date 2/12/2017, resolution 1 m





Jérémie_2016: classification map obtained from the application of the proposed algorithm; Producer Accuracy (PA) and Overall Accuracy (OA)

		PA
WATER		100%
URBAN		100%
TALL VEG		96,70%
LOW VEG		95,50%
MUDDY WATER		100%
	OA	98,40%



Jérémie_2017: classification map obtained from the application of the proposed algorithm; Producer Accuracy (PA) and Overall Accuracy (OA)

		PA
WATER		97.4%
URBAN		100%
TALL VEG		100%
LOW VEG		97%
BARE SOIL		100%
	OA	99%





Change-map derived from the application of the proposed method

Highlighted transition:

MUDDY WATER - WATER	
MUDDY WATER - BARESOIL	
URBAN - BARE SOIL	
WATER - BARE SOIL	
URBAN - LOW VEG	
LOW VEG - URBAN	



Detail: Urban area. RGB composition Jérémie_2017 (left), RGB composition Jérémie_2016 (center) and change-map (right) Gray scale visualization in the change-map is related to no-change transitions.





Detail: Mouth of the river Grande Anse. RGB composition Jérémie_2016 (a), classification map Jérémie_2016 (b), RGB composition Jérémie_2017 (c), classification map Jérémie_2017 (d), RGB composition Jérémie_2017 - 2m resolution (e), and change map (f)





Jérémie_2016: Classification map generated through MSVC-GC



Jérémie_2016: Classification map generated through RF



Jérémie_2016: Classification map obtained through the proposed approach





Urban area of Jeremie_2016, RGB composition

(a)



Urban area of Jeremie_2017, RGB composition



Obtained Change-map



(b)

URBAN - VEG	
URBAN - GRASS	
VEG - URBAN	
VEG - GRASS	
GRASS - URBAN	
GRASS - VEG	

Detail: Urban area of Jerèmie. RGB composition Jérémie_2016 (a), RGB composition Jérémie_2017 (b), and change map (c). Gray scale visualization in the change-map is related to no-change transitions.

(c)



- Change detection and identification of land cover classes and land cover transitions
- Characterization of the typology of the occurred changes
- High Overall Accuracy on the test set

Conclusions

- Applicability to images characterized by an arbitrary probability distribution function
- Significant improvement wrt the initial classification map used for the PMF estimation
- Limited sensitivity to the number of segmentation maps used



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